

GAURAV MISRA

CONTACT INFORMATION	2700 Camino Ramon, 140 San Ramon, CA 94583, USA	Phone: 575-495-0823 gaurav.misra@rutgers.edu misraga.github.io
TECHNICAL INTERESTS	Aerospace systems, Robotics, Nonlinear control, Constrained optimization, Machine learning	
COMPUTER SKILLS	MATLAB, Simulink, C++, Python, Yalmip, AMPL, NumPy, SciPy, Scikit-learn	
EDUCATION	Rutgers, The State University of New Jersey , New Brunswick, NJ, USA Doctor of Philosophy, Mechanical and Aerospace Engineering, October 2019 <ul style="list-style-type: none">• Thesis Topic: <i>Tractable optimization based control and learning for space-robotic systems.</i>• Advisor: Prof. Xiaoli Bai New Mexico State University , Las Cruces, NM, USA Master of Science, Aerospace Engineering, May 2015 <ul style="list-style-type: none">• Thesis Topic: <i>Dynamics and control of rigid body spacecraft near small solar system bodies</i>• Advisor: Prof. Amit Sanyal Birla Institute of Technology and Science, Pilani , India Bachelor of Engineering (Honors), Electronics and Instrumentation, July 2013	
RESEARCH EXPERIENCE	Graduate Research Assistant Dept. of Mechanical and Aerospace Engineering, Rutgers University	Aug 2016 to Present
	<ul style="list-style-type: none">• Convex optimization based trajectory planning technique for free-floating space robots.• State-feedback and output-feedback stochastic model predictive control (MPC) based controllers for flight control in turbulence.• Sum-of-squares programming based framework for synthesis of disturbance observer based controllers.	
	Graduate Research Assistant Dept. of Mechanical and Aerospace Engineering, New Mexico State University	Jan 2014 to May 2015
	<ul style="list-style-type: none">• Coupled orbit-attitude dynamics and controllability of spacecraft near small solar system bodies, and its implications on spacecraft proximity operations.	
	Research Intern IMCCE, Observatoire de Paris, France Topic: Trajectory optimization and control of aerospace vehicles Supervisor: Florent Deleflie	Jan 2013 to June 2013
	Bachelor Thesis Student French Space Agency (CNES), Toulouse, France Topic : Modeling of Yarkovsky effect for numerical propagation of orbital trajectories. Supervisor: Jean-Yves Prado	July 2012 to Dec 2012
	Summer Research Intern German Aerospace Center (DLR), Bremen, Germany Topic : Computational analysis for spacecraft missions to Near Earth Asteroids Supervisor: Dominik Quantius	May 2011 to July 2011

PUBLICATIONS
UNDER REVIEW

1. **Misra, G.**, Bai, X. “Disturbance Estimation and Rejection for Aircraft Glideslope Regulation in Turbulence : A Matrix SOS Approach”, *IEEE American Control Conference (ACC)*, Denver, 2020.
2. **Misra, G.**, Bai, X. “Robust Disturbance Observer based Control for Relative Attitude Tracking using Sum-of-squares Programming”, *Journal of Guidance, Control, and Dynamics*

JOURNAL
PUBLICATIONS

1. Wang, L., **Misra, G.**, and Bai, X. “A K Nearest Neighborhood Based Wind Estimation for Rotary-Wing VTOL UAVs.” *Drones*, 3, 31 (2019).
2. **Misra, G.**, Bai, X. “Output-feedback Stochastic Model Predictive Control for Glideslope Control during Aircraft Carrier Landing.” *Journal of Guidance, Control, and Dynamics*, Vol. 42, No. 9, (2019).
3. **Misra, G.**, Bai, X. “Task-Constrained Trajectory Planning of Space-Robotic Systems using Convex Optimization.” *Journal of Guidance, Control, and Dynamics*, Vol. 40, No. 11 (2017), pp. 2857-2870.
4. **Misra, G.**, Bai, X. “Optimal Path Planning of Free-flying Space Manipulators using Sequential Convex Programming”, *Journal of Guidance, Control, and Dynamics*, Vol. 40, No. 11 (2017), pp. 3026-3033..
5. **Misra, G.**, Izadi, M., Sanyal, A. K., and Scheeres, D. J. “Coupled orbit-attitude dynamics and relative state estimation of spacecraft near small bodies.” *Advances in Space Research*, Vol. 57, No. 8 (2016), pp 1747-1761.

CONFERENCE
PROCEEDINGS

1. **Misra, G.**, Bai, X. “Iteratively Feasible Optimal Spacecraft Guidance using Convex Optimization”, *AIAA Guidance, Navigation, and Control Conference, Florida, 2020*.
2. **Misra, G.**, Bai, X. “Updated Simulation Results of UAV Carrier Landings”, *AIAA Modeling and Simulation Technologies Conference, Florida, 2020*.
3. **Misra, G.**, Bai, X. “Nonlinear Disturbance Observer based Control for Polynomial Systems with Mismatched Uncertainties using Sum-of-Squares Programming”, *IEEE American Control Conference (ACC)*, Philadelphia, 2019.
4. **Misra, G.**, Gao, T., and Bai, X. “Modeling and Simulation of UAV Carrier Landings”, *AIAA Modeling and Simulation Technologies Conference, San Diego, 2019*.
5. **Misra, G.**, Bai, X. “Stochastic Model Predictive Control for Gust Alleviation during Aircraft Carrier Landing”, *IEEE American Control Conference (ACC)*, Milwaukee, 2018.
6. **Misra, G.**, Peng, H, and Bai, X. “Halo Orbit Station-keeping using Nonlinear MPC and Polynomial Optimization”, *28th AIAA/AAS Spaceflight Mechanics Meeting, Kissimmee, FL, 2018*.
7. **Vishawanathan S. P.**, Sanyal, A. K., and Misra, G. “Controllability analysis of spacecraft with only attitude actuation near small solar system bodies”, *10th IFAC Symposium on Nonlinear Control Systems (NOLCOS)*, Monterey, CA, 2016.
8. **Misra, G.**, Samiei, E., and Sanyal, A. K. “Asteroid landing guidance design in the framework of coupled orbit-attitude spacecraft dynamics.” *25th AAS/AIAA Spaceflight Mechanics Meeting*, Williamsburg, VA, 2015.
9. **Misra, G.**, and Sanyal, A. K. “Analysis of orbit-attitude coupling of spacecraft near small solar system bodies.” *AIAA Guidance, Navigation and Control Conference*, Kissimmee, FL, 2015.
10. **Sanyal, A. K.**, Izadi, M., Misra, G., Samiei, E., and Scheeres, D. J. “Estimation of dynamics of space objects from visual feedback during proximity operations.” *AIAA Astrodynamics Specialist Conference*, San Diego, CA, 2014.

CONFERENCE
PRESENTATIONS
(WITHOUT
PROCEEDINGS)

1. **Quantius, D.**, Misra, G., Löscher, M., and Maiwald, V. "List of potential target Near Earth Objects (NEOs) for human missions." *64th International Astronautical Congress*, Beijing, China 2013.
2. **Misra, G.** "Asteroid hazard mitigation via Yarkovsky effect reduction." *IAA Planetary Defense Conference*, Flagstaff, Arizona 2013.

REVIEWER
ACTIVITIES

- IEEE American Control Conference (ACC)
- AIAA Modeling and Simulation Technologies Conference
- AIAA Guidance, Navigation, and Control Conference (GNC)
- AIAA Journal of Guidance, Control and Dynamics
- IEEE Conference on Advanced Intelligent Mechatronics (AIM)
- IEEE Transactions on Aerospace and Electronic Systems
- Celestial Mechanics and Dynamical Astronomy
- Journal of Robotics

AWARDS/
HONORS

- American Control Conference Travel Award, 2019.
- American Control Conference Travel Award, 2018.
- Rutgers TA/GA Professional Development Fund, 2016, 2017, 2018.
- Rutgers School of Graduate Studies (SGS) Conference Travel Award, 2017.
- BITS Alumni Association (BITSAA) Conference Travel Award, 2010.
- NASA/NSS Space Settlement Award, 2008.

WORKSHOPS/
SUMMER
SCHOOLS

- First American Model Predictive Control Summer School, UW Madison, Wisconsin, 2017.
- Sokendai Asian Winter School, Japanese Aerospace Exploration Agency (JAXA), 2015.

COURSEWORK

- Robotics, Convex Optimization, Advanced Control, Machine Learning, Stochastic Programming, Dynamic Programming, Calculus of Variations, Advanced Dynamics, Satellite Design, Nonlinear and Optimal Control

REFERENCES

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